On the mass term of the Dirac equation

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Abstract

We consider the generalization of the Dirac equation where the mass term is an arbitrary matrix M. A general form of M, consistent with the mass shell constraint, is derived and proven to be equivalent to the original Dirac equation.

1 Introduction

The original way [1] in which Dirac obtained relativistic equation for fermions seems to leave certain ambiguities related to the choice of the mass term. This led some authors [2] to discuss the possibility of generalizing the term by considering certain mass matrices M instead of the usual matrix $m\mathbf{1}$. We would like to point out that consistency conditions actually imply that M must be given by $M = me^{(i\alpha-\beta)\gamma^5}$ with $\alpha \in [0, 2\pi]$ and $\beta \in \mathbb{R}$, of which the cases $\beta = 0$ and $\alpha = 0$ were discussed in [2]. The mass term M can be obtained from the Dirac

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equation by an appropriate change of the phases and the norms of the Weyl spinors.

2 General mass term

Consider a non hermitian x^{μ} dependent matrix M and assume that the corresponding Dirac equations $D_M \psi = 0$, $D_M = -i\gamma^{\mu}\partial_{\mu} + M$ holds. For an arbitrary operator \mathcal{D} the consistency conditions $\mathcal{D}D_M \psi = 0$ have to be satisfied. Due to the mass shell constraint $p_{\mu}p^{\mu} = m^2$, $p_{\mu} = -i\partial_{\mu}$, useful conditions will come from operators \mathcal{D} which involve the $i\gamma^{\mu}\partial_{\mu}$ operator. Let us consider

$$0 = D_{-M}D_M\psi = (m^2 - M^2 - i\gamma^\mu\partial_\mu M)\psi - i[\gamma^\mu, M]\partial_\mu\psi \qquad (1)$$

(we use the conventions $\eta_{\mu\nu} = diag(1, -1, -1, -1), \{\gamma^{\mu}, \gamma^{\nu}\} = 2\eta^{\mu\nu}\mathbf{1}, \gamma^{5} = +i\gamma^{0}\gamma^{1}\gamma^{2}\gamma^{3}$). One can also consider other equations e.g.

$$0 = D_{-M\dagger} D_M \psi = D_M D_M \psi = D_{M\dagger} D_M \psi = D_{\mathbf{0}} D_M \psi \tag{2}$$

however as it turns out they do not give new constraints.

If M is equal to $m\mathbf{1}$, equation (1) is trivially satisfied (equations in (2) are either trivial or give the Dirac equation $D_m\psi=0$). For general M we obtain some nontrivial, first order, differential equations for ψ . These equations must reduce to the Dirac equation $D_M\psi=0$ - otherwise we would obtain an independent equation for fermions. Concentrating on Eqn. (1) we conclude that

$$[\gamma^{\mu}, M] = A\gamma^{\mu},\tag{3}$$

$$m^2 - M^2 - i\gamma^{\mu}\partial_{\mu}M = AM \tag{4}$$

for some matrix A.

In order to solve (3) and (4) it is useful to multiply Eqn. (3) from the r.h.s. by γ^{μ} (no sum) which in particular implies the following equations

$$\gamma^i M \gamma^i - \gamma^j M \gamma^j = 0, \quad 1 \le i < j \le 3.$$

Using explicit representation for gamma matrices we find that the general solution of the letter is

$$M = a(x) + b(x)\gamma^5, \quad a(x), b(x) \in \mathbb{C}$$
 (5)

which using (3) gives $A = -2b(x)\gamma^5$ hence (4) gives

$$m^{2} = a(x)^{2} - b(x)^{2} + \gamma^{\mu} \partial_{\mu} \left(a(x) + b(x) \gamma^{5} \right).$$
 (6)

The r.h.s. in (6) should be proportional to the unit matrix hence $\partial_{\mu}a = \partial_{\mu}b = 0$. Therefore the general solution of (3) and (4) and hence of the constraint (1) is given by

$$M = a + b\gamma^5, \quad a, b \in \mathbb{C},$$

$$m^2 = a^2 - b^2. \tag{7}$$

It turns out that (7) also solves other constraint (2). Let us consider the first equation in (2)

$$0 = D_{-M^{\dagger}} D_M \psi = (m^2 - M^{\dagger} M - i \gamma^{\mu} \partial_{\mu} M) \psi - i (\gamma^{\mu} M - M^{\dagger} \gamma^{\mu}) \partial_{\mu} \psi.$$
(8)

The equations following from (8) are

$$\gamma^{\mu}M - M^{\dagger}\gamma^{\mu} = B\gamma^{\mu},\tag{9}$$

$$m^2 - M^{\dagger}M = BM \tag{10}$$

for some matrix B. Substituting (7) to (9) we find that

$$B = 2i|a|\sin\alpha - 2|b|\cos\beta\gamma^5$$
, $\alpha := Arg(a)$, $\beta := Arg(b)$

which substituted to (10) gives two equations

$$m^2 - |a|^2 - |b|^2 = 2ia|a|\sin\alpha - 2b|b|\cos\beta,$$
 (11)

$$-2|a||b|\cos(\alpha-\beta) = 2i|a|b\sin\alpha - 2a|b|\cos\beta. \tag{12}$$

Equation (11) is actually equivalent to the second equation in (7) while (12) is an identity hence (8) gives no new constraints on a and b. The same conclusion holds for the remaining equations in (2).

Using the parametrization for the complex circle in (7)

$$a = m(\cos \alpha \cosh \beta - i \sin \alpha \sinh \beta),$$

$$b = mi(\sin\alpha \cosh\beta + i\cos\alpha \sinh\beta)$$

with $\alpha \in [0, 2\pi]$ and $\beta \in \mathbb{R}$ we can write M in the compact form

$$M = me^{(i\alpha - \beta)\gamma^5}. (13)$$

Finally let us observe that this form of M can be obtained from the Dirac equation with $M=m\mathbf{1}$. Noting that in the Weyl representation we have

$$i\sigma^{\mu}\partial_{\mu}\psi_{L} = me^{-i\alpha+\beta}\psi_{R},$$

 $i\bar{\sigma}^{\mu}\partial_{\mu}\psi_{R} = me^{i\alpha-\beta}\psi_{L}.$

where ψ_R , ψ_L are Weyl spinors and choosing $\tilde{\psi}_L = e^{\frac{i\alpha-\beta}{2}}\psi_L$, $\tilde{\psi}_R = e^{-\frac{i\alpha-\beta}{2}}\psi_R$ (which could be interpreted as the chiral transformation with the complex angle) the Dirac equation for Weyl spinors $\tilde{\psi}_R$, $\tilde{\psi}_L$ transforms into the standard form with M=m.

It is interesting to note that choosing M not belonging to (13) breaks in general the explicit relativistic invariance of equations. As an example let us consider $M=m\gamma_0$. The condition (1) implies that $i\gamma^j\partial_j\psi=0$ and hence $(i\partial_0-m)\psi=0$ which clearly is not Lorentz invariant. This example is particularly interesting (among other choices e.g. $M=\gamma^i$) as there are no negative energy solutions for this choice i.e. the plane-wave ansatz $\psi=ue^{-ikx}$ for positive energy solutions and $\psi=ve^{ikx}$ for negative energy solutions, implies $k_i=0$, $k_0=m$ for four basis spinors $[u_s]_t=\delta_{st}$, s,t=1,2,3,4 and no solutions for the v spinor.

3 Conclusions

In this paper we considered generalizations of the Dirac equation where the mass term is replaced by an arbitrary matrix M. It follows that a simple consistency condition (1) implies that M must be of the form (13) which in turn can be obtained from the original Dirac equation by a suitable redefinition of the wavefunction. Therefore the choice $M=m\mathbf{1}$ is already general.

References

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